

5.2. Cluster Analysis

- o Aim: group n objects into k classes
- o $k \ll n$, k often unknown
- o Objects within classes are "close" to each other
objects in different classes are well discriminable.
- o Needed: metric of closeness & discriminability

5.2.1 k-means clustering

Given data $x_1, \dots, x_n \in \mathbb{R}^P$

Aim: Partition data into clusters

S_1, \dots, S_k (a partition of $\{1, \dots, n\}$) and
centers $\mu_1, \dots, \mu_k \in \mathbb{R}^P$
as a solution to

$$\min_{\substack{S_1, \dots, S_k \text{ part. of } \{1, \dots, n\} \\ \mu_1, \dots, \mu_k \in \mathbb{R}^P}} \sum_{e=1}^k \sum_{i \in S_e} \|x_i - \mu_e\|^2 \quad (\text{NP-hard})$$

- Given the partition, the optimum centers are

$$\mu_e = \bar{x}_e = \frac{1}{n_e} \sum_{i \in S_e} x_i$$

$$n_e = \# S_e$$

- The k-means algorithm, Lloyd's alg.

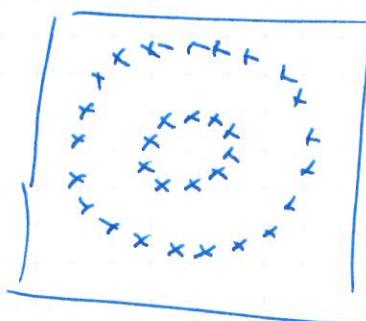
Alternate between

- Given centers μ_1, \dots, μ_k , assign x_i to the cluster $l = \arg \min_j \|x_i - \mu_j\|$
- Update the centers $\mu_l = \frac{1}{n_l} \sum_{i \in S_l} x_i$, $l = 1, \dots, k$

Remarks:

- Needs the no of clusters k a priori.
- Needs a Euclidean space.
- May end in a suboptimal solution
- Solution has always "convex" clusters

How to cluster?



5.2.2. Spectral clustering

Given x_1, \dots, x_n

Construct a weighted graph $G = (V, E, W)$

Each points x_i represents a vertex v_i .

Edges weights w_{ij} are $w_{ij} = K_\varepsilon(\|x_i - x_j\|)$

with a kernel K_ε , e.g., $K_\varepsilon(u) = \exp\left\{-\frac{1}{2\varepsilon} u^2\right\}$

Note: $\|x_i - x_j\|$ can be substituted by any dissimilarity measure.

Consider a random walk with transition matrix

$$M = D^{-1}W$$

$$P(X_{t+1} = j | X_t = i) = \frac{w_{ij}}{\deg(i)} = M_{ij}$$

$$D = \text{diag}(\deg(i)), \quad \deg(i) = \sum_{l=1}^n w_{il}.$$

$$\text{Decompose } M = \Phi \Lambda \Psi^\top = \sum_{k=1}^n \lambda_k \varphi_k \psi_k^\top$$

(see 4.3 "diffusion maps")

$$\Lambda = \text{diag}(\lambda_1, \dots, \lambda_n), \quad \lambda_1 \geq \dots \geq \lambda_n$$

$\Phi = (\varphi_1, \dots, \varphi_n)$, $\Psi = (\psi_1, \dots, \psi_n)$ biorthogonal, i.e.,

$$\Phi^\top \Psi = I_n \Leftrightarrow \varphi_i^\top \psi_j = \delta_{ij}.$$

φ_i, ψ_j right and left eigenvectors of M .

Then $M^t = \sum_{k=1}^n \lambda_k^t \varphi_k \psi_k^T$

$$\begin{aligned} v_i \Leftrightarrow e_i M^t &= \sum_{k=1}^n \lambda_k^t \underbrace{e_i \varphi_k}_{\text{coefficients}} \psi_k^T \\ &= \sum_{k=1}^n \underbrace{\lambda_k^t \varphi_{k,i}}_{\text{coefficients}} \underbrace{\psi_k^T}_{\text{orthonormal basis}} \end{aligned}$$

Diffusion map truncated to α dimensions

$$\phi_t^{(\alpha)}(i) = \begin{pmatrix} \lambda_2^t \varphi_{2,i} \\ \vdots \\ \lambda_{\alpha+1}^t \varphi_{\alpha+1,i} \end{pmatrix} \quad (\text{see 4.3})$$

Aim: cluster the vertices of the graph in k clusters.

Algorithm 5.3 (spectral clustering)

Given a graph $G = (V, E, W)$, no. of clusters k , t .

Compute the $(k-1)$ -dim. diffusion map

$$\phi_t^{(k-1)}(i) = \begin{pmatrix} \lambda_2^t \varphi_{1,i} \\ \vdots \\ \lambda_k^t \varphi_{k,i} \end{pmatrix}$$

and cluster $\phi_t^{(k-1)}(1), \dots, \phi_t^{(k-1)}(n) \in \mathbb{R}^{k-1}$ using, e.g.,
 k -means clustering.

5.2.3. Hierarchical Clustering

Method is based on dissimilarities between objects.

Given n objects v_1, \dots, v_n and pairwise dissimilarities

$$\delta_{ij} = \delta_{ji}, \quad \Delta = (\delta_{ij})_{1 \leq i, j \leq n}$$

Define a linkage function between clusters C_1, C_2

$$d(C_1, C_2) = \begin{cases} \min_{i \in C_1, j \in C_2} \delta_{ij} & \text{single linkage} \\ \max_{i \in C_1, j \in C_2} \delta_{ij} & \text{complete linkage} \\ \frac{1}{\#C_1 \#C_2} \sum_{\substack{i \in C_1 \\ j \in C_2}} \delta_{ij} & \text{average linkage} \end{cases}$$

Algorithm: (agglomerative clustering)

Initialize clusters as singleton: for $i=1 \dots n$ do $C_i \leftarrow \{c_i\}$.

Initialize the set of clusters for merging: $S \leftarrow \{1, \dots, n\}$

repeat

pick 2 most similar clusters to merge: $(j, k) \in S$

$$(j, k) \leftarrow \underset{j, k \in S}{\operatorname{arg\,min}} d(C_j, C_k)$$

Create new cluster $C_e \leftarrow C_j \cup C_k$

Mark j and k as unavailable: $S \leftarrow S \setminus \{j, k\}$

If $C_e \notin \{1, \dots, n\}$ then

mark e as available $S \leftarrow S \cup \{e\}$

For each $i \in S$ do

update the dissimilarity matrix $d(C_i, C_e)$

Until no more clusters are available for merging.

Cut off, if a certain threshold is exceeded by $d(C_i, C_j)$

Visualization by dendograms or binary trees.

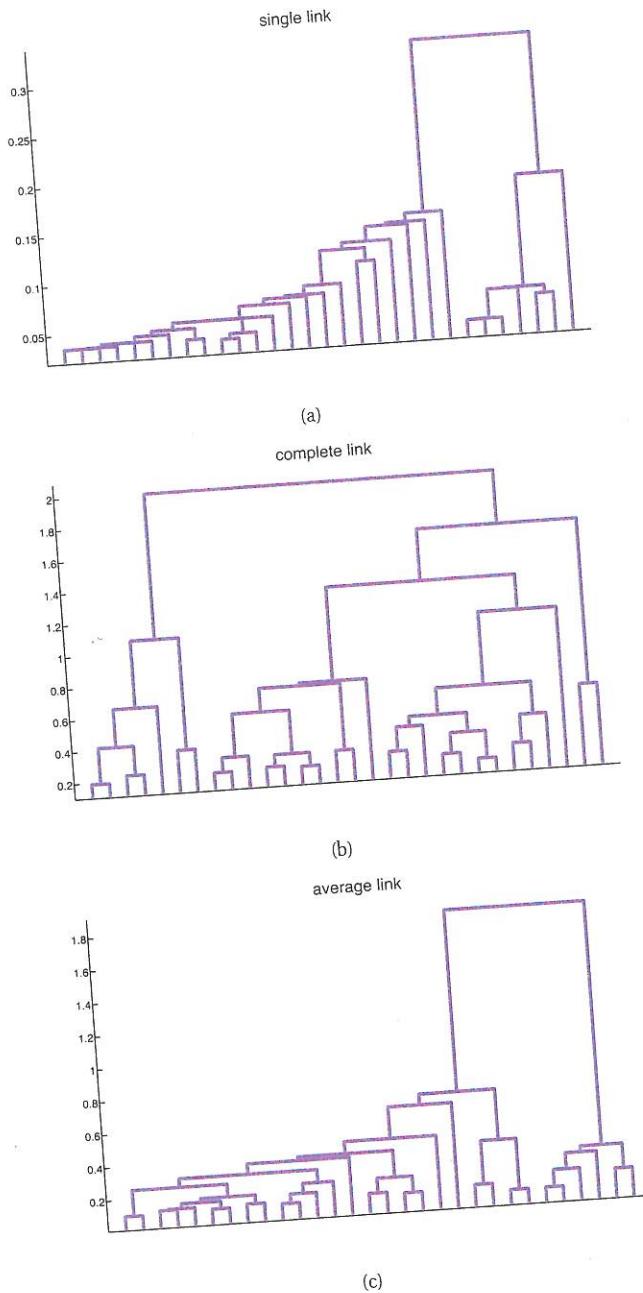


Figure 25.15 Hierarchical clustering of yeast gene expression data. (a) Single linkage. (b) Complete linkage. (c) Average linkage. Figure generated by `hclustYeastDemo`.

From: Murphy : Machine Learning