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## Exercise 11

### - Proposed Solution -

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### Solution of Problem 1

a) The first step is to formulate the Lagrangian function:

$$\Lambda(\mathbf{x}, \boldsymbol{\lambda}) = \mathbf{c}^T \mathbf{x} + \boldsymbol{\lambda}^T (\mathbf{A}\mathbf{x} - \mathbf{b}) = (\mathbf{c} + \mathbf{A}^T \boldsymbol{\lambda})^T \mathbf{x} - \boldsymbol{\lambda}^T \mathbf{b}$$

$\boldsymbol{\lambda}$  is Lagrange multiplier. Next step is to find Lagrange dual function:

$$g(\boldsymbol{\lambda}) = \inf_{\mathbf{x} \in \mathbb{R}^n} \Lambda(\mathbf{x}, \boldsymbol{\lambda}) = \begin{cases} -\boldsymbol{\lambda}^T \mathbf{b} & \mathbf{c} + \mathbf{A}^T \boldsymbol{\lambda} = 0 \\ -\infty & \text{otherwise.} \end{cases}$$

Therefore the dual problem can be written as:

$$\begin{aligned} \max \quad & -\mathbf{b}^T \boldsymbol{\lambda} \\ \text{s.t.} \quad & \mathbf{A}^T \boldsymbol{\lambda} + \mathbf{c} = 0 \\ & \boldsymbol{\lambda} \succeq 0 \end{aligned}$$

b) Again, the first step is to formulate the Lagrangian function:

$$\Lambda(\mathbf{x}, \boldsymbol{\lambda}) = \mathbf{x}^T \mathbf{B}\mathbf{x} + \boldsymbol{\lambda}^T (\mathbf{A}\mathbf{x} - \mathbf{b})$$

Next step is to find Lagrange dual function:

$$g(\boldsymbol{\lambda}) = \inf_{\mathbf{x} \in \mathbb{R}^n} \Lambda(\mathbf{x}, \boldsymbol{\lambda})$$

Using derivation with respect to  $\mathbf{x}$ , we have:

$$\frac{\partial}{\partial \mathbf{x}} \Lambda(\mathbf{x}, \boldsymbol{\lambda}) = 2\mathbf{B}\mathbf{x} + \mathbf{A}^T \boldsymbol{\lambda} \implies \mathbf{x} = -\frac{1}{2} \mathbf{B}^{-1} \mathbf{A}^T \boldsymbol{\lambda}.$$

Having this solution (verify that it is the minimum point indeed), the Lagrange dual function is given by:

$$g(\boldsymbol{\lambda}) = \frac{1}{4} \boldsymbol{\lambda}^T \mathbf{A} \mathbf{B}^{-1} \mathbf{A}^T \boldsymbol{\lambda} + \boldsymbol{\lambda}^T \left( -\frac{1}{2} \mathbf{A} \mathbf{B}^{-1} \mathbf{A}^T \boldsymbol{\lambda} - \mathbf{b} \right) = -\frac{1}{4} \boldsymbol{\lambda}^T \mathbf{A} \mathbf{B}^{-1} \mathbf{A}^T \boldsymbol{\lambda} - \boldsymbol{\lambda}^T \mathbf{b}$$

Therefore the dual problem can be written as:

$$\begin{aligned} \max \quad & -\frac{1}{4} \boldsymbol{\lambda}^T \mathbf{A} \mathbf{B}^{-1} \mathbf{A}^T \boldsymbol{\lambda} - \boldsymbol{\lambda}^T \mathbf{b} \\ \text{s.t.} \quad & \boldsymbol{\lambda} \succeq 0 \end{aligned}$$

c) Again, the first step is to formulate the Lagrangian function:

$$\Lambda(\mathbf{x}, \boldsymbol{\nu}) = \|\mathbf{x}\|_p + \boldsymbol{\nu}^T(\mathbf{A}\mathbf{x} - \mathbf{b})$$

Next step is to find Lagrange dual function:

$$g(\boldsymbol{\nu}) = \inf_{\mathbf{x} \in \mathbb{R}^n} \Lambda(\mathbf{x}, \boldsymbol{\nu})$$

A related optimization problem can be written as:

$$\inf_{\mathbf{x}} \|\mathbf{x}\|_p + \mathbf{a}^T \mathbf{x}.$$

Consider the Hölder's inequality:

$$\|\mathbf{x}\|_p \|\mathbf{a}\|_q \geq |\mathbf{a}^T \mathbf{x}| \geq -\mathbf{a}^T \mathbf{x},$$

if  $\frac{1}{p} + \frac{1}{q} = 1$ . Note that if  $\|\mathbf{a}\|_q \leq 1$ , then  $\|\mathbf{x}\|_p + \mathbf{a}^T \mathbf{x} \geq 0$  and therefore  $\inf_{\mathbf{x}} \|\mathbf{x}\|_p + \mathbf{a}^T \mathbf{x} = 0$ .

Now suppose that  $\|\mathbf{a}\|_q > 1$ . See that if  $\mathbf{x} = -t(a_1|a_1|^{q-2}, \dots, a_n|a_n|^{q-2})$  for some  $t > 0$ , then we have:

$$\|\mathbf{x}\|_p + \mathbf{a}^T \mathbf{x} = t\|\mathbf{a}\|_q^{q-1} - t\|\mathbf{a}\|_q^q = t(\|\mathbf{a}\|_q^{q-1} - \|\mathbf{a}\|_q^q).$$

Since  $\|\mathbf{a}\|_q > 1$ , the above expression is strictly negative and can be arbitrarily small when  $t \rightarrow \infty$ .

Applying the above result, the Lagrange dual function is given by:

$$g(\boldsymbol{\nu}) = \inf_{\mathbf{x} \in \mathbb{R}^n} \Lambda(\mathbf{x}, \boldsymbol{\nu}) = \begin{cases} -\boldsymbol{\nu}^T \mathbf{b} & \|\mathbf{A}^T \boldsymbol{\nu}\|_q \leq 1 \\ -\infty & \text{otherwise.} \end{cases}$$

Therefore the dual problem can be written as:

$$\begin{aligned} \max \quad & -\boldsymbol{\nu}^T \mathbf{b} \\ \text{s.t.} \quad & \|\mathbf{A}^T \boldsymbol{\nu}\|_q \leq 1 \end{aligned}$$

## Solution of Problem 2

a) The first step is to formulate the Lagrangian function:

$$\Lambda(\mathbf{a}, b, \boldsymbol{\xi}, \boldsymbol{\alpha}, \boldsymbol{\lambda}) = \frac{1}{2}\|\mathbf{a}\|^2 + c \sum_{i=1}^n \xi_i - \sum_{i=1}^n \lambda_i [y_i(\mathbf{a}^T \mathbf{x}_i + b) - 1 + \xi_i] - \sum_{i=1}^n \alpha_i \xi_i,$$

where  $\lambda_i, \alpha_i \geq 0$  and we know that  $y_i = 1$  or  $-1$ .

Next step is to find Lagrange dual function:

$$g(\boldsymbol{\lambda}, \boldsymbol{\alpha}) = \inf_{\boldsymbol{\xi}, \mathbf{a} \in \mathbb{R}^n, b \in \mathbb{R}} \Lambda(\mathbf{a}, b, \boldsymbol{\xi}, \boldsymbol{\alpha}, \boldsymbol{\lambda})$$

Taking the derivation with respect to these parameters lead to:

$$\frac{\partial}{\partial \mathbf{a}} \Lambda(\mathbf{a}, b, \boldsymbol{\xi}, \boldsymbol{\alpha}, \boldsymbol{\lambda}) = 0 \implies \mathbf{a} = \sum_{i=1}^n \lambda_i y_i \mathbf{x}_i$$

$$\frac{\partial}{\partial b} \Lambda(\mathbf{a}, b, \boldsymbol{\xi}, \boldsymbol{\alpha}, \boldsymbol{\lambda}) = 0 \implies 0 = \sum_{i=1}^n \lambda_i y_i$$

$$\frac{\partial}{\partial \boldsymbol{\xi}} \Lambda(\mathbf{a}, b, \boldsymbol{\xi}, \boldsymbol{\alpha}, \boldsymbol{\lambda}) = 0 \implies c = \lambda_i + \alpha_i \quad i = 1, \dots, n$$

Using these assumptions, the dual problem can be written as:

$$\begin{aligned} \max \quad & \sum_{i=1}^n \lambda_i - \frac{1}{2} \sum_{i,j} y_i y_j \lambda_i \lambda_j \mathbf{x}_i^T \mathbf{x}_j \\ \text{s.t.} \quad & 0 \leq \lambda_i \leq c \\ & \sum_{i=1}^n \lambda_i y_i = 0. \end{aligned}$$

- b) Take two support vector  $\mathbf{x}_k$  and  $\mathbf{x}_l$  with  $y_k = 1$  and  $y_l = -1$ . Those support vectors are those with  $0 < \lambda < c$ . Then since for support vectors we have  $y_i(\mathbf{a}^T \mathbf{x}_i + b) = 1$ , we have:

$$(\mathbf{a}^{*T} \mathbf{x}_k + b^*) = -(\mathbf{a}^{*T} \mathbf{x}_l + b^*) \implies b^* = \frac{-1}{2} \mathbf{a}^{*T} (\mathbf{x}_k + \mathbf{x}_l) \quad (1)$$

In litterature, somethimes an average is calculated over all support vectors for better robustness.

### Solution of Problem 3

- a)  $b$  is given as  $-\frac{1}{2} \mathbf{a}^T (\mathbf{x}_1 + \mathbf{x}_2) = 3$ .

- b) Supporting vectors are those with  $\lambda_i \neq 0$ , which are  $\mathbf{x}_2, \mathbf{x}_3, \mathbf{x}_4, \mathbf{x}_5$ .

$\mathbf{x}_i$	$y_i$	$\lambda_i$	$\mathbf{x}_i$	$y_i$	$\lambda_i$
$\mathbf{x}_1 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$	$y_1 = -1$	$\lambda_1 = 0$	$\mathbf{x}_4 = \begin{pmatrix} 0.5 \\ -0.5 \end{pmatrix}$	$y_4 = 1$	$\lambda_4 = 4.73$
$\mathbf{x}_2 = \begin{pmatrix} 2 \\ 0 \end{pmatrix}$	$y_2 = -1$	$\lambda_2 = 0.67$	$\mathbf{x}_5 = \begin{pmatrix} -2 \\ 1 \end{pmatrix}$	$y_5 = 1$	$\lambda_5 = 0.94$
$\mathbf{x}_3 = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$	$y_3 = -1$	$\lambda_3 = 5$	$\mathbf{x}_6 = \begin{pmatrix} 0 \\ -1 \end{pmatrix}$	$y_6 = 1$	$\lambda_6 = 0$

- c) For those vectors, the normal vector of the hyperplane is obtained as:

$$\mathbf{a} = \sum_{i=1}^6 \lambda_i y_i \mathbf{x}_i = \lambda_2 y_2 \mathbf{x}_2 + \lambda_3 y_3 \mathbf{x}_3 + \lambda_4 y_4 \mathbf{x}_4 + \lambda_5 y_5 \mathbf{x}_5$$

$$\mathbf{a} = -0.67 \begin{pmatrix} 2 \\ 0 \end{pmatrix} - 5 \begin{pmatrix} 0 \\ 0 \end{pmatrix} + 4.73 \begin{pmatrix} 0.5 \\ -0.5 \end{pmatrix} + 0.94 \begin{pmatrix} -2 \\ 1 \end{pmatrix} = \begin{pmatrix} -0.86 \\ -1.43 \end{pmatrix}$$

To find  $b$ , take two support vectors  $\mathbf{x}_k$  and  $\mathbf{x}_l$  with  $y_k = 1$  and  $y_l = -1$  with  $0 < \lambda < 5$ . For these support vectors, we have  $y_i(\mathbf{a}^T \mathbf{x}_i + b) = 1$ . Hence:

$$b^* = \frac{-1}{2} \mathbf{a}^{*T} (\mathbf{x}_k + \mathbf{x}_l) = -\frac{1}{2} \begin{pmatrix} -0.86 & -1.43 \end{pmatrix} \left( \begin{pmatrix} 2 \\ 0 \end{pmatrix} + \begin{pmatrix} -2 \\ 1 \end{pmatrix} \right) = \frac{1.43}{2} = 0.715. \quad (2)$$